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②

Theory of Ensembles

A macrostate $\{E, V, N\}$ corresponds to a huge set of μ -states of number $\Omega(E, V, N)$.

These states are equally probable.



After long enough time we can assume that the time average = ensemble average

The Ergodic assumption $\langle f(t) \rangle = \langle f \rangle_{\text{ensemble}}$.
This is why looking at ensembles is so useful to us.

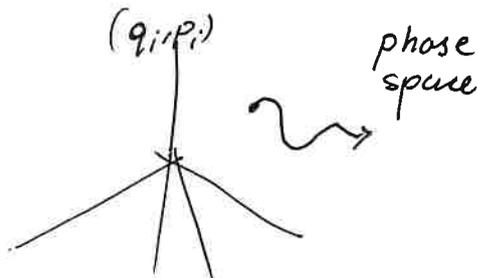
②.1 Phase space of a classical system

μ -state of a classical system is defined by specifying all positions and momenta of the particles:

$$+ \begin{cases} 3N \text{ positions } q_1, q_2, \dots, q_{3N} & (x_i, y_i, z_i) \\ 3N \text{ momenta } p_1, p_2, \dots, p_{3N} & (p_x, p_y, p_z) \end{cases}$$

This set is a point in $\mathbb{R}^{6N} \equiv$ PHASE SPACE
 (q_i, p_i)

This point evolves in time

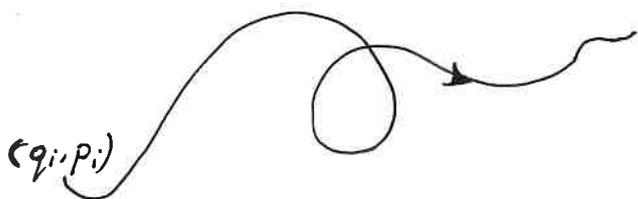


The time evolution is determined by the canonical equations of motion (a.k.a. Hamilton's Eqs.)

$$\left\{ \begin{array}{l} \dot{q}_i = \frac{\partial \mathcal{H}}{\partial p_i} \\ \dot{p}_i = -\frac{\partial \mathcal{H}}{\partial q_i} \end{array} \right\} \quad \begin{array}{l} 6N \text{ equations} \\ i = 1, 2, \dots, 3N \end{array}$$

• The function $\mathcal{H}(q_i, p_i)$ is the Hamiltonian.

(\dot{q}_i, \dot{p}_i) is the velocity vector in phase space



example: free particle in gravity

$$\mathcal{H} = \frac{p_x^2 + p_y^2 + p_z^2}{2m} + mgz$$

$$\dot{x} = \frac{p_x}{m}; \quad \dot{y} = \frac{p_y}{m}; \quad \dot{z} = \frac{p_z}{m}$$

$$\dot{p}_x = 0; \quad \dot{p}_y = 0; \quad \dot{p}_z = -mg$$

• Usually the trajectory is limited to a finite region in phase space

$$q_i \in V$$

E limits both p_i, q_i through $\mathcal{H}(p, q)$

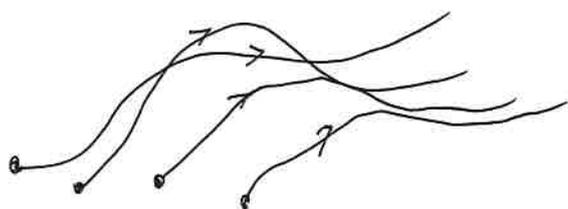
• In particular if total energy is conserved

hypersurface

$$\mathcal{H}(q_i, p_i) = E = \text{const.}$$

If E is not accurately determined the trajectory is in the hypershell $(E - \frac{\Delta}{2}, E + \frac{\Delta}{2})$.

• The movement of an ensemble of ρ -states:



- We can describe the motion by the density function $\rho(q, p, t)$

$$q_i \quad p_i \quad i=1, \dots, 3N$$

$\int d^{3N}p d^{3N}q \rho = \#$ of systems (points) in $d^{3N}q d^{3N}p$

- The density function tells the distribution of μ -states in phase space, as a function of time.
- We can now define the ensemble average of a quantity $f(q, p)$

$$\langle f \rangle = \frac{\int f(q, p) \rho(q, p, t) d^{3N}q d^{3N}p}{\int \rho(q, p, t) d^{3N}q d^{3N}p}$$

integration
over whole Phase Space

- * Note that $\langle f \rangle$ may be a function of time.
- * The ensemble is stationary if ρ does not depend on time explicitly

$$\boxed{\frac{\partial \rho}{\partial t} = 0}$$

This implies that $\Rightarrow \frac{\partial \langle f \rangle}{\partial t} = 0$ as well

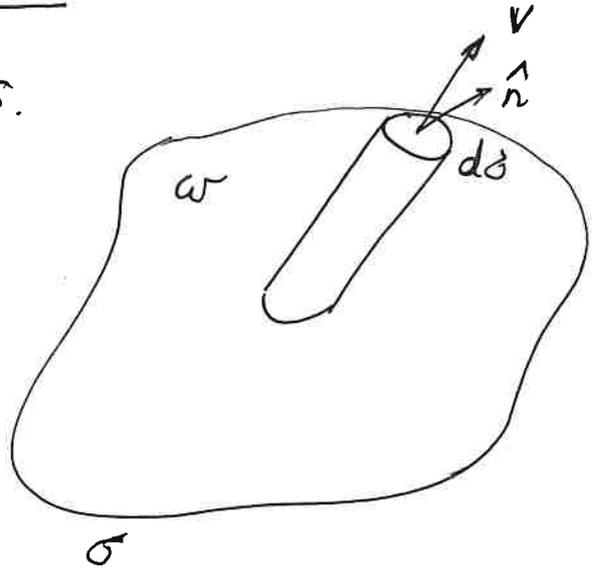
- * Of course, a system at equilibrium is stationary.

Liouville's theorem

Consider a volume $\omega \in P.S.$
with surface σ

$$\left. \begin{array}{l} \text{rate of} \\ \text{change} \\ \text{\# systems} \end{array} \right\} = \frac{\partial}{\partial t} \int_{\omega} \rho \, d\omega$$

$$\text{where } d\omega = d^{3N}q \, d^{3N}p$$



On the other hand, the rate is also equal to
the flux through the surface

$$\int_{\sigma} \rho \vec{v} \cdot \hat{n} \, d\sigma = \int_{\omega} \text{div}(\rho \vec{v}) \, d\omega$$

divergence theorem

Here, divergence is

$$\text{div}(\rho \vec{v}) = \sum_{i=1}^{3N} \frac{\partial}{\partial q_i} (\rho \dot{q}_i) + \sum_{i=1}^{3N} \frac{\partial}{\partial p_i} (\rho \dot{p}_i)$$

Since points do not appear/disappear spontaneously

$$\frac{\partial}{\partial t} \int_{\omega} \rho \, d\omega = - \int \text{div}(\rho \vec{v}) \, d\omega$$

$$\Rightarrow \int_{\omega} \left[\frac{\partial \rho}{\partial t} + \text{div}(\rho \vec{v}) \right] d\omega = 0$$

\Rightarrow

$$\boxed{\frac{\partial \rho}{\partial t} + \text{div}(\rho \vec{v}) = 0}$$

equation
of
continuity

$$\frac{\partial \rho}{\partial t} + \sum_{i=1}^{3N} \left(\frac{\partial \rho}{\partial q_i} \dot{q}_i + \rho \frac{\partial \dot{q}_i}{\partial q_i} \right) + \sum_{i=1}^{3N} \left(\frac{\partial \rho}{\partial p_i} \dot{p}_i + \rho \frac{\partial \dot{p}_i}{\partial p_i} \right) = 0$$

$$\Rightarrow \frac{\partial \rho}{\partial t} + \sum_{i=1}^{3N} \left(\frac{\partial \rho}{\partial q_i} \dot{q}_i + \frac{\partial \rho}{\partial p_i} \dot{p}_i \right) + \rho \sum_{i=1}^{3N} \left(\frac{\partial \dot{q}_i}{\partial q_i} + \frac{\partial \dot{p}_i}{\partial p_i} \right) \equiv 0$$

$$\frac{\partial \dot{q}_i}{\partial q_i} = \frac{\partial^2 \mathcal{H}}{\partial p_i \partial q_i} \quad \frac{\partial \dot{p}_i}{\partial p_i} = \frac{\partial}{\partial p_i} \left(- \frac{\partial \mathcal{H}}{\partial q_i} \right) = - \frac{\partial^2 \mathcal{H}}{\partial p_i \partial q_i}$$

$$\Rightarrow \frac{\partial \rho}{\partial t} + \sum_{i=1}^{3N} \left(\frac{\partial \rho}{\partial q_i} \frac{\partial \mathcal{H}}{\partial p_i} - \frac{\partial \rho}{\partial p_i} \frac{\partial \mathcal{H}}{\partial q_i} \right)$$

this is the Poisson bracket $[\rho, \mathcal{H}]$

$$\frac{d\rho}{dt} = \frac{\partial \rho}{\partial t} + \sum_{i=1}^{3N} \left(\frac{\partial \rho}{\partial q_i} \dot{q}_i + \frac{\partial \rho}{\partial p_i} \dot{p}_i \right) = \frac{\partial \rho}{\partial t} + [\rho, \mathcal{H}] = 0$$

Liouville's theorem The total time derivative

of the density vanishes. \mathcal{O}_t : in a f.o.r.

moving with the systems $\rho = \text{const.}$

* The "fluid" in P.S. is incompressible.

* If $[\rho, \mathcal{H}] = 0$ then also $\frac{\partial \rho}{\partial t} = 0$

Of course if ρ is independent of coordinates

$$[\rho, \mathcal{H}] = 0$$

This corresponds to an ensemble that uniformly distributed over all μ -states at all times.

Then the ensemble average is

$$\langle f \rangle = \frac{1}{\omega} \int f(q, p) d\omega \quad \text{because } \rho = \rho_0$$

\Rightarrow any point is equally likely
[postulate of equal prob.]

* Another way to satisfy $\frac{\partial \rho}{\partial t} = 0$ is to have

$$\begin{aligned} \text{Then} \quad & \frac{\partial \rho}{\partial q_i} \frac{\partial \mathcal{H}}{\partial p_i} - \frac{\partial \rho}{\partial p_i} \frac{\partial \mathcal{H}}{\partial q_i} \\ & = \frac{\partial \rho}{\partial \mathcal{H}} \frac{\partial \mathcal{H}}{\partial q_i} \frac{\partial \mathcal{H}}{\partial p_i} - \frac{\partial \rho}{\partial \mathcal{H}} \frac{\partial \mathcal{H}}{\partial p_i} \frac{\partial \mathcal{H}}{\partial q_i} = 0 \end{aligned}$$

For example if $\rho(q, p) \sim e^{-\mathcal{H}(q, p)/T}$ $\frac{\partial \rho}{\partial t} = 0$

2.3 The microcanonical Ensemble

- Macrostate is defined by (N, V, E) .
- Equivalently we can define hyper-shell $[E - \frac{\Delta}{2}, E + \frac{\Delta}{2}]$
- Each of the μ -states is equally probable.
- The shell is defined $E - \frac{1}{2}\Delta \leq \mathcal{H}(q, p) \leq E + \frac{1}{2}\Delta$

* The microcanonical ensemble is a collection of systems with a density function ρ

$$\rho = \begin{cases} \rho(q, p) = \text{const.} & \text{in shell} \\ 0 & \text{outside} \end{cases}$$

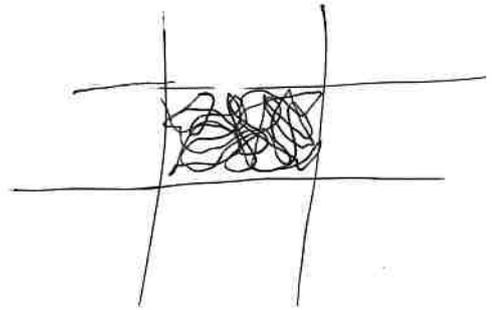
* The ensemble average is stationary $\frac{\partial \langle f \rangle}{\partial t} = 0$

$$\langle f \rangle = \overline{\langle f \rangle} \stackrel{\sim \text{time average}}{=} \langle \bar{f} \rangle = \bar{f} \stackrel{\text{measurement}}{=} f_{\text{exp}}$$

↑ averages are independent ↑ same for all members of ensemble

Ensemble average of any physical quantity $\langle f \rangle$ is equal to the expected value of measurement f_{exp}

Ergodic theorem (Boltzmann): After long enough time, A μ -state will pass through all states in the relevant phase space



We want to connect between the mechanics of μ -states and the TD of the macrostate

We know that $\Gamma \propto \omega$

↑ # of states ↑ volume of hypershell

We need to find the fundamental volume ω_0 of 1 μ -state

Then $(\Omega =) \Gamma = \frac{\omega}{\omega_0} \Rightarrow S = \ln \Gamma = \ln \left(\frac{\omega}{\omega_0} \right)$ etc.

The scaling of ω_0 is $(\Delta x \cdot \Delta p)^{3N} \sim h^{3N}$ | postpone

2.4 Examples

A. Ideal gas:

$$\sum_i \frac{p_i^2}{2m} = E$$

$$\omega = \int_{\Gamma} d^{3N}q \int d^{3N}p = V^N \int d^3p$$

$$E - \frac{\Delta}{2} \leq \sum \frac{p_i^2}{2m} \leq E + \frac{\Delta}{2}$$

We can compare to counting states

$$\left. \begin{aligned} \sum_{r=1}^{3N} n_r^2 &= \frac{8mV^{2/3}}{h^2} E = \left(\frac{V^{1/3} 2\sqrt{2mE}}{h} \right)^2 \\ \sum_{r=1}^{3N} p_r^2 &= (\sqrt{2mE})^2 \end{aligned} \right\}$$

$$\omega \sim V^N (2mE)^{\frac{3N}{2}}$$

$$\Gamma \sim \left(\frac{V^{1/3} 2\sqrt{2mE}}{h} \right)^{3N} \frac{1}{2^{3N}} = \frac{V^N (2mE)^{3N/2}}{h^{3N}}$$

$$\rightarrow \boxed{\omega_0 = h^{3N}}$$

B. Harmonic oscillator



$$H(q, p) = \frac{1}{2} K q^2 + \frac{p^2}{2m}$$

$$\left. \begin{array}{l} \text{Hamilton's} \\ \text{equation} \end{array} \right\} \begin{cases} \dot{q} = \frac{p}{m} \\ \dot{p} = m\ddot{q} = -Kq \end{cases} \quad \text{Newton's law}$$

$$q = A \cos(\omega t + \phi) \quad \omega = \sqrt{\frac{K}{m}}$$

$$p = m\dot{q} = -m\omega A \sin(\omega t + \phi)$$

$$E = \frac{1}{2} k q^2 + \frac{p^2}{2m} = \frac{1}{2} k A^2 \cos^2(\omega t + \phi) + \frac{\omega^2 A^2}{2m} \sin^2(\dots)$$

$$= \frac{1}{2} k A^2 = \frac{1}{2} m \omega^2 A^2 = \text{const.}$$

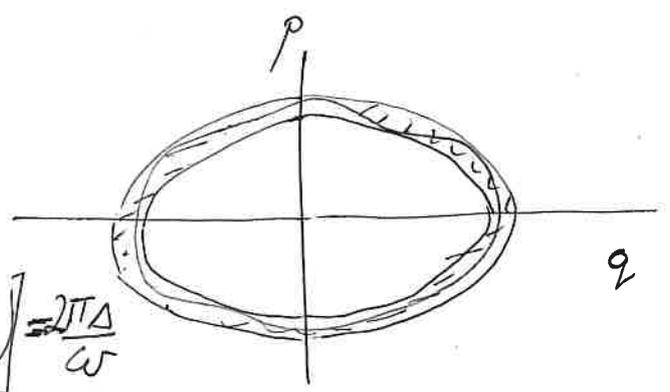
This defines phase-space

$$\left(\frac{x}{E} = \right) \frac{p^2}{2mE} + \frac{q^2}{(2E/m\omega^2)} = 1 \quad \text{an ellipse}$$

$$\text{Area} = \pi ab = \frac{2\pi E}{\omega}$$

As usual we consider the hypershell $(E - \frac{\Delta}{2}, E + \frac{\Delta}{2})$

With volume



$$W = \int d^3q dp = \frac{2\pi}{\omega} \left[(E + \frac{\Delta}{2}) - (E - \frac{\Delta}{2}) \right] = \frac{2\pi\Delta}{\omega}$$

From Q.M we know the energies of the oscillator

$$E_n = (n + \frac{1}{2}) \hbar \omega \quad n = 0, 1, 2, \dots$$

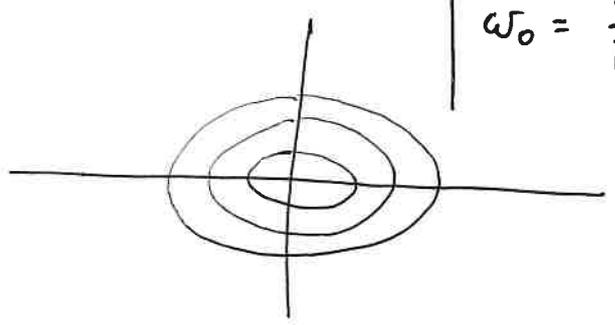
So the shell that corresponds to one state has $\Delta E = \hbar \omega$

So that

$$\omega_0 = \frac{2\pi}{\omega} \hbar \omega = 2\pi \hbar = h$$

$$\frac{E}{\omega_0} = \Gamma$$

$$\omega_0 = \frac{h}{E}$$



If $E \gg \Delta \gg \hbar \omega$ the number of eigenstates is $\frac{\Delta}{\hbar \omega}$

Similarity for N oscillators $\omega_0 = h^N$

2.5 Quantum States and the Phase Space

Why h is so significant?

The uncertainty principle:

We cannot specify simultaneously both the position and momentum of a particle.

$$(\Delta q \Delta p) \geq \hbar$$

This tells that around every point (q, p) there is a region where the system could be.



So we can think of P.S. cells where all positions in a cell are non-distinct.

Relativistic particles (photons)

$$p = \hbar k = \hbar \frac{\omega}{c}$$

Then

$$\int d^3q d^3p = V \cdot 4\pi p^2 dp = V 4\pi \left(\frac{\hbar}{c}\right)^3 \omega^2 d\omega$$

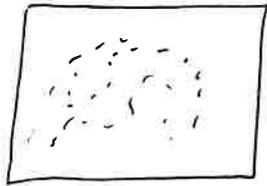
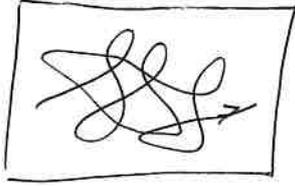
Rayleigh had an expression for # of states

$$V \cdot (4\pi) (2\pi)^3 \frac{\omega^2 d\omega}{c^3}$$

from which we see that $\omega_0 = h^3$

Summary CH. 2

* Ensembles in Phase Space:



$$dw = d^{3N}q d^{3N}p$$

$$\bar{f} = \langle f \rangle$$

* Density function $\rho(q, p, t)$

obey Liouville's theorem

$$\frac{d\rho}{dt} = \frac{\partial \rho}{\partial t} + [\rho, H] = 0$$

* Stationary system $\frac{\partial \rho}{\partial t} = 0$ equilibrium

* Microcanonical Ensemble

Macrostate (E, V, N)

constant E manifold $\mathcal{H} = E$

$$\Omega = \frac{1}{h^{3N} N!} \int dw \delta(\mathcal{H} - E)$$